Lower Bounds for some Algebraic Models of Computation

Prerona Chatterjee

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- design a computational model that captures the constraints
- study the amount of resource required by the model to complete the task.

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Given a boolean function f on ninputs, how many steps are required by a Turing machine to compute the f (in terms of n)?



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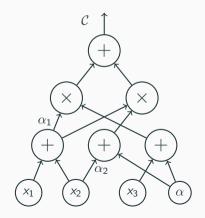
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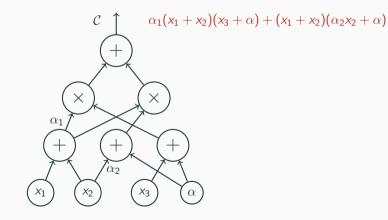
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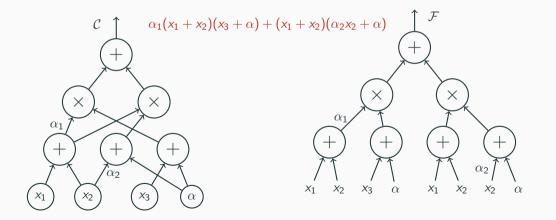
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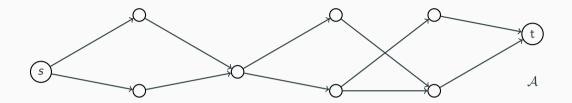
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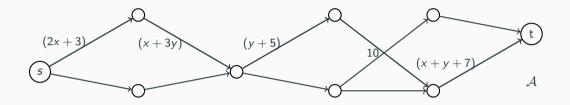
[Shamir 79, Lipton 94]: If $h(x) = \prod_{i=1}^{d} (x - i)$ can be computed using poly(log d) additions and multiplications, then integer factoring is easy for boolean circuits.



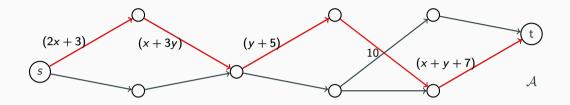




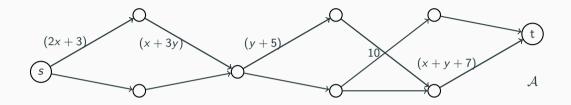




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- Polynomial computed by the ABP: $f_{\mathcal{A}}(\mathbf{x}) = \sum_{p} \operatorname{wt}(p)$

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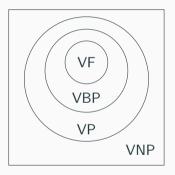


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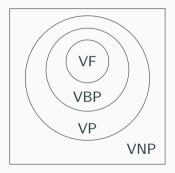
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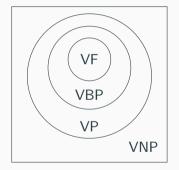
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Central Question: Find explicit polynomials that cannot be computed by efficient circuits. **Other Motivating Questions**: Are the other inclusions tight?

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[C-Kumar-She-Volk 22]: Any formula computing $\text{ESYM}_{n,0.1n}(\mathbf{x})$ requires $\Omega(n^2)$ vertices.

$$\mathrm{ESYM}_{n,d}(\mathbf{x}) = \sum_{i_1 < \cdots < i_d \in [n]} x_{i_1} \cdots x_{i_d}.$$

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Ultimate Goal: Prove better than func(s, n, d) lower bounds.

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[C-Kush-Saraf-Shpilka 24]: For $\omega(\log n) = d \le n$, there is a polynomial $G_{n,d}(\mathbf{x})$ which is set-multilinear w.r.t $\mathbf{x} = {\mathbf{x}_1, \ldots, \mathbf{x}_d}$, where $|\mathbf{x}_i| \le n$ for every $i \in [d]$, such that:

- $G_{n,d}$ is computable by a set-multilinear ABP of size poly(n),
- any $\sum \text{osmABP}$ computing $G_{n,d}$ must have super-polynomial total-width.

The variable set is divided into buckets.

$$\mathbf{x} = \mathbf{x}_1 \cup \cdots \cup \mathbf{x}_d$$
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An ABP is set-multilinear with respect to $\{\mathbf{x}_1, \dots, \mathbf{x}_d\}$ if every path in it

computes a set-multilinear monomial with respect to $\{\mathbf{x}_1, \ldots, \mathbf{x}_d\}$.

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[C-K-S-S 24]: Super polynomial lower bound against total-width of $\sum \text{osmABP}$ for a polynomial of degree $d = \omega(\log n)$ that is computable by polynomial-sized ABPs.

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Further, there is a non-commutative circuit of size $O(n \log^2 n)$ that computes $OSym_{n,n/2}(\mathbf{x})$.

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position indices \equiv bucket indices

Tight Separation in a Structured Setting

 $\{X_1, \ldots, X_m\}$: Partition of the underlying set of variables $\{x_1, \ldots, x_n\}$.

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[Cha 21]: For $\mathbf{x} = \bigcup_{i \in [n]} \{X_i\}$ with $X_i = \{x_{i,j}\}_{j \in [n]}$, there exists a (log *n*)-degree abecedarian polynomial $f \in \mathbb{F} \langle \mathbf{x} \rangle$ such that

- There is an abecedarian ABP of size O(nd) that computes f.
- Any abecedarian formula computing f has size $n^{\Omega(\log \log n)}$.
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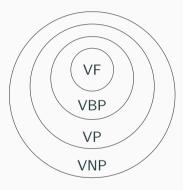
If an *n*-variate polynomial is abecedarian with respect to $\{X_1, \ldots, X_m\}$ for $m = \log n$,

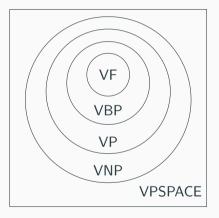
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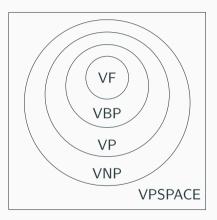
If an *n*-variate polynomial is abecedarian with respect to $\{X_1, \ldots, X_m\}$ for $m = \log n$, then any formula computing *f* can be made abecedarian with only poly(*n*) blow-up in size.





Classes Beyond VNP

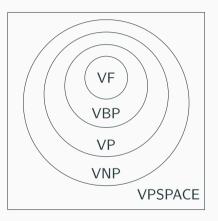
 $\label{eq:constraint} \begin{array}{l} \mbox{[Koiran-Perifel 09]} \\ \mbox{VNP} \neq \mbox{VPSPACE}_b \implies \mbox{P/poly} \neq \mbox{PSPACE/poly}. \end{array}$



Classes Beyond VNP

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 $\mathsf{VNP} \stackrel{?}{=} \mathsf{VPSPACE}_b$

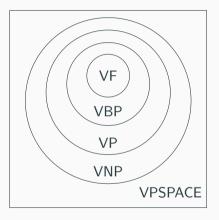


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[C-Gajjar-Tengse 23]: $VNP \neq VPSPACE_b$ in the monotone setting.

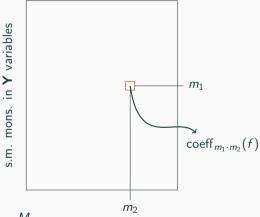


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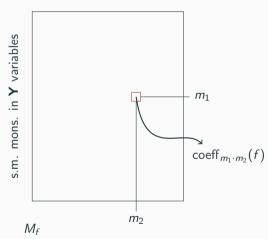




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Note: Γ is almost always the dimension of some algebraic object and most of the time is simply the rank of a matrix associated with f. The property "a matrix has low-rank" can be captured by a polynomial equation.

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Proof Overview of Lower Bound against Sum of osmABPs

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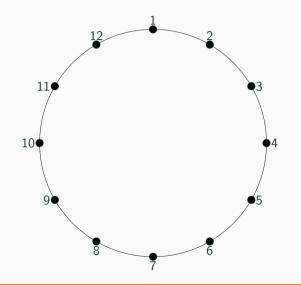
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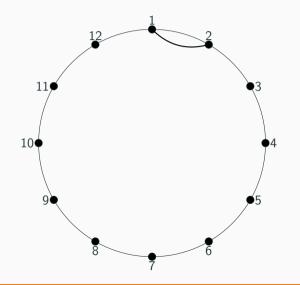
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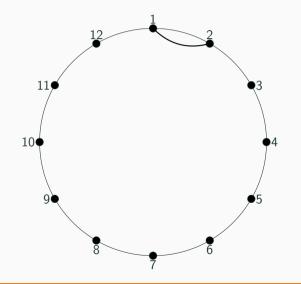
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- any ordered set-multilinear branching program computing $G_{n,d}$ requires width $n^{\Omega(d)}$.

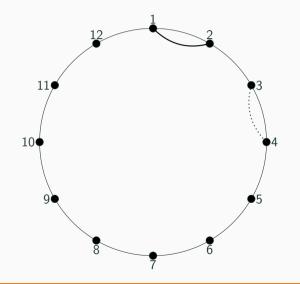
Arc Partition



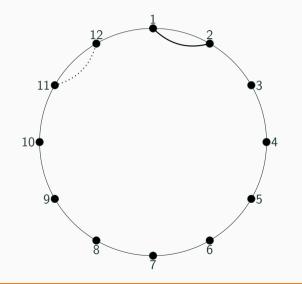




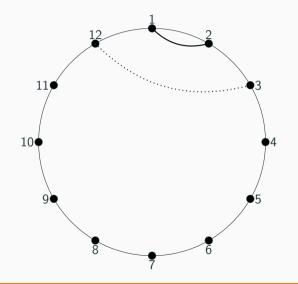
$$\mathcal{P}_1 = \{(1,2)\}$$



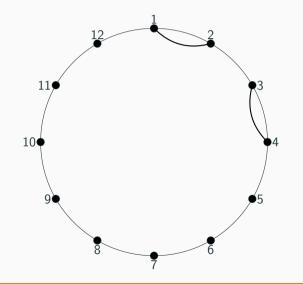
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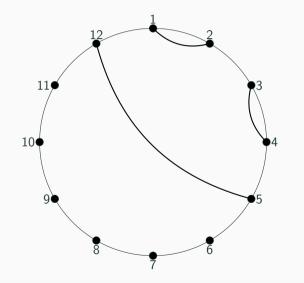
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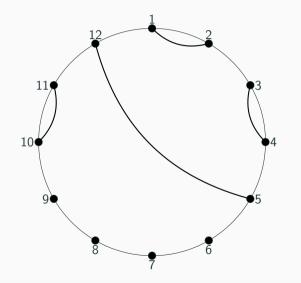


$$\mathcal{P}_1 = \{(1,2)\}$$
 $\mathcal{P}_2 = \{(1,2),(3,4)\}$

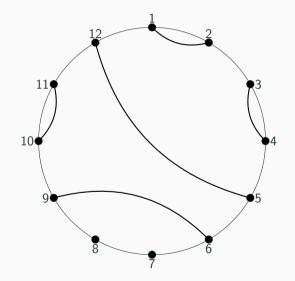


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$$\begin{aligned} \mathcal{P}_1 &= \{(1,2)\} \\ \mathcal{P}_2 &= \{(1,2),(3,4)\} \\ \mathcal{P}_3 &= \{(1,2),(3,4),(12,5)\} \\ \mathcal{P}_4 &= \{(1,2),(3,4),(12,5),(10,11)\} \end{aligned}$$



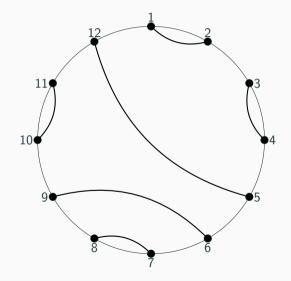
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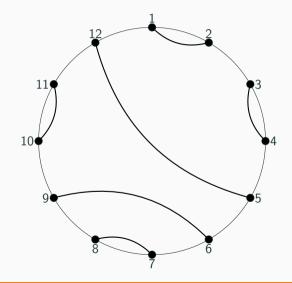
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$$\mathcal{P}_{5} = \{(1,2), (3,4), (12,5), (10,11), (9,6)\}$$



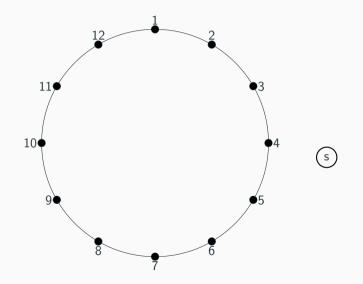
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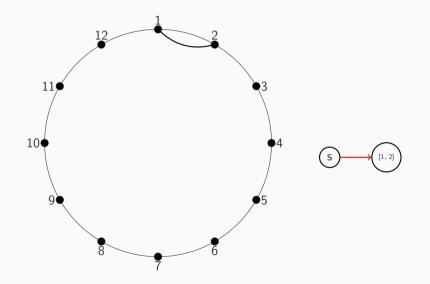


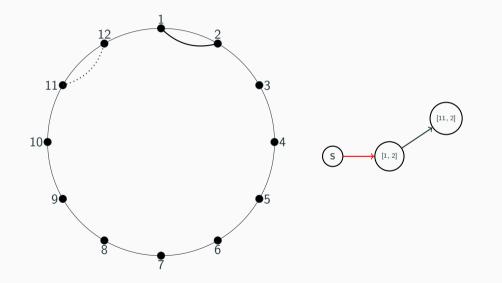
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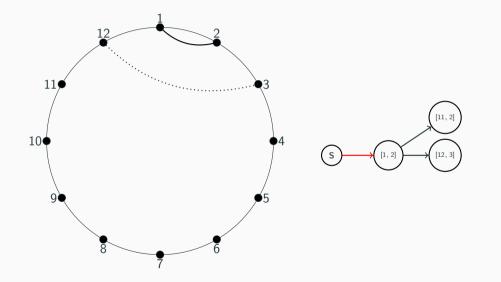
 $\mathbf{P}_6 = AII$ possibles sequences of such pairs.

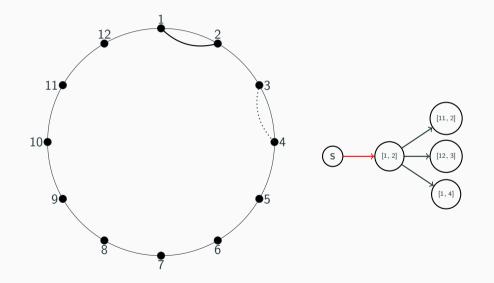
L

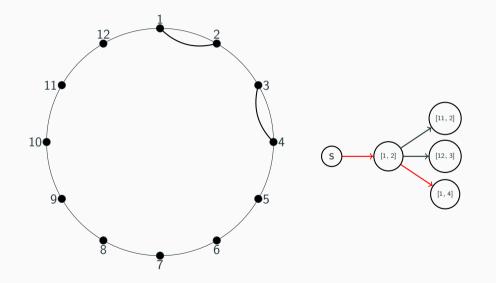


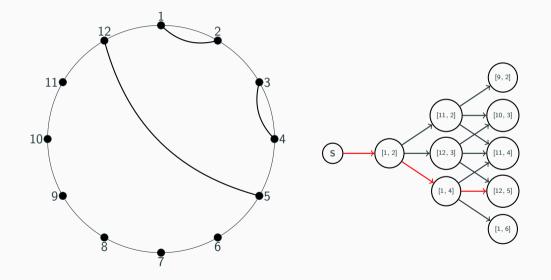


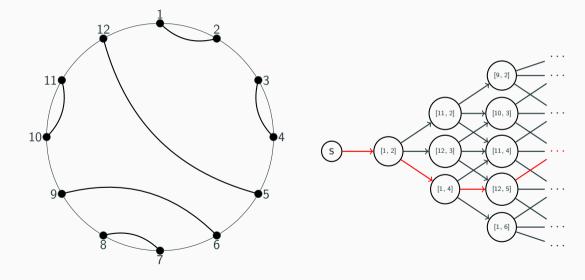


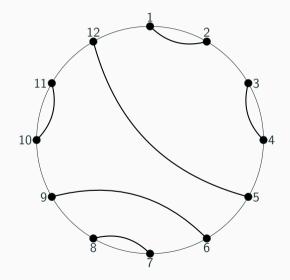




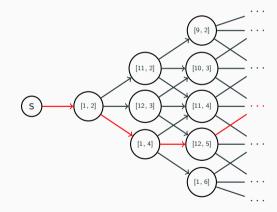








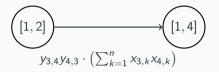
Every path corresponds to an element in $P_{d/2}$.

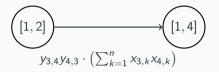


The Hard Polynomial

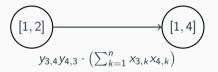






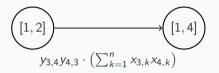


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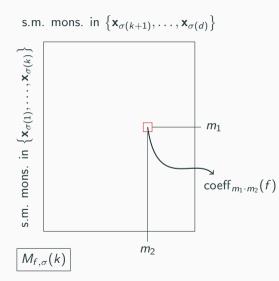
 $\left(\sum_{k=1}^{n} x_{3,k} x_{4,k}\right)$: To achieve full-rank.



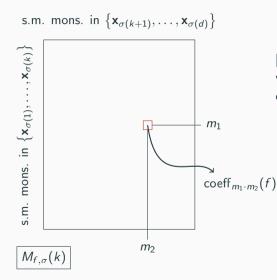
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	<i>x</i> _{4,1}	<i>x</i> _{4,2}	 	<i>x</i> _{4,<i>n</i>}
<i>x</i> _{3,1}	1	0	 	0
<i>x</i> _{3,2}	0	1	 	0
:	:	÷		÷
÷	÷	÷		÷
<i>x</i> _{3,<i>n</i>}	0	0	 	1

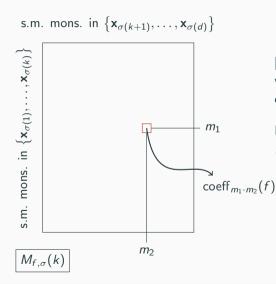


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If \mathcal{A} is the smallest osmABP (in order σ) computing f, then

$$\mathsf{size}(\mathcal{A}) = \sum_{i=1}^{d} \mathsf{rank}(M_{f,\sigma}(k)).$$

Lower Bound for a single osmABP (contd.)

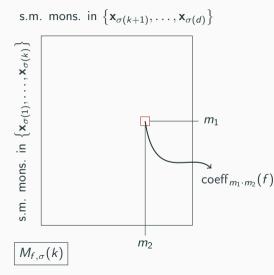
$$G_{n,d} = \sum_{\mathcal{P} \in \mathbf{P}_{d/2}} \prod_{(i,j) \in \mathcal{P}} y_{i,j} y_{j,i} \cdot \left(\sum_{k=1}^n x_{i,k} x_{j,k} \right).$$

Lower Bound for a single osmABP (contd.)

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Properties:

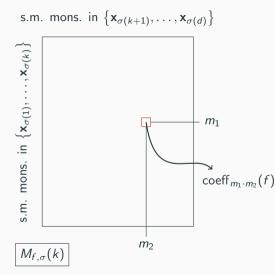
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Properties:

- *G_{n,d}* is computable by a set-multilinear ABP of size poly(*n*, *d*).
- For every $\sigma \in S_d$, there is some \mathcal{P} such that for at least d/8 of the $P = (i, j) \in \mathcal{P}$, $i \in$ $\{\sigma(1), \ldots \sigma(\frac{d}{2})\} \& j \in \{\sigma(1 + \frac{d}{2})), \ldots \sigma(d)\}.$



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Therefore,

$$\operatorname{rank}(M_{G_{n,d},\sigma}(d/2)) = \Omega(n^{d/8}).$$

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- If $G_{n,d}$ is computed by a sum of t osmABPs, then

$$G_{n,d} = \sum_{i=1}^{t} g_i$$
 where $g_i = \sum_{u_1,...,u_{q-1}} \prod_{j=1}^{q} g_{u_{j-1},u_j}^{(i)}$

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$$G_{n,d} = \sum_{i=1}^t g_i \quad ext{where} \quad g_i = \sum_{u_1, \dots, u_{q-1}} \prod_{j=1}^q g_{u_{j-1}, u_j}^{(i)}.$$

• Define a distribution D on S such that when $w \sim D$, if g_i s are computable by osmABPs efficiently, then

- $\{M_w(f) : w \in S\}$ is a set of matrices such that $M_w(G_{n,d})$ has full rank for every $w \in S$.
- If $G_{n,d}$ is computed by a sum of t osmABPs, then

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• Define a distribution D on S such that when $w \sim D$, if g_i s are computable by osmABPs efficiently, then

for every *i*, w.h.p. there are many *j*s, for which $M_w(g_{u_{i-1},u_i}^{(i)})$ is far from full rank

- $\{M_w(f) : w \in S\}$ is a set of matrices such that $M_w(G_{n,d})$ has full rank for every $w \in S$.
- If $G_{n,d}$ is computed by a sum of t osmABPs, then

$$G_{n,d} = \sum_{i=1}^t g_i \quad ext{where} \quad g_i = \sum_{u_1, \dots, u_{q-1}} \prod_{j=1}^q g_{u_{j-1}, u_j}^{(i)}.$$

• Define a distribution \mathcal{D} on \mathcal{S} such that when $w \sim \mathcal{D}$, if g_i s are computable by osmABPs efficiently, then

for every *i*, w.h.p. there are many *j*s, for which $M_w(g_{u_{j-1},u_j}^{(i)})$ is far from full rank \implies for every *i*, w.h.p. $M_w(g_i)$ is far from full rank

- $\{M_w(f) : w \in S\}$ is a set of matrices such that $M_w(G_{n,d})$ has full rank for every $w \in S$.
- If $G_{n,d}$ is computed by a sum of t osmABPs, then

$$G_{n,d} = \sum_{i=1}^t g_i \quad ext{where} \quad g_i = \sum_{u_1, \dots, u_{q-1}} \prod_{j=1}^q g_{u_{j-1}, u_j}^{(i)}.$$

• Define a distribution D on S such that when $w \sim D$, if g_i s are computable by osmABPs efficiently, then

for every *i*, w.h.p. there are many *j*s, for which $M_w(g_{u_{j-1},u_j}^{(i)})$ is far from full rank

 \implies for every *i*, w.h.p. $M_w(g_i)$ is far from full rank

 $\implies M_w(G_{n,d})$ is far from full rank unless *t* is large.

Ongoing and Future Projects

• Better lower bounds against homogeneous formulas?

- Better lower bounds against homogeneous formulas?
- Super-linear Lower Bounds against ABPs for constant degree polynomials?

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- Super-linear Lower Bounds against Determinantal Complexity?

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- Better lower bounds against set-multilinear ABPs?
- Better Lower Bounds against Non-Commutative circuits?
- Separating formulas and ABPs in the non-commutative setting?
- Do VP have VP natural proofs under some reasonable conditions?

Branching Out

Study complexity theoretic questions about Boolean Circuits, Communication Models.

The courses I would be happy to teach:

- Computing Lab -I
- Computing Lab-II
- Discrete Mathematical Structures
- Linear Algebra for Computer Science
- Programming and Data Structures
- Algorithms
- Theory of Computation
- Linear Programming and Convex Optimization

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Given enough time, I should be able to teach some of the other compulsory courses as well.

Thank you!